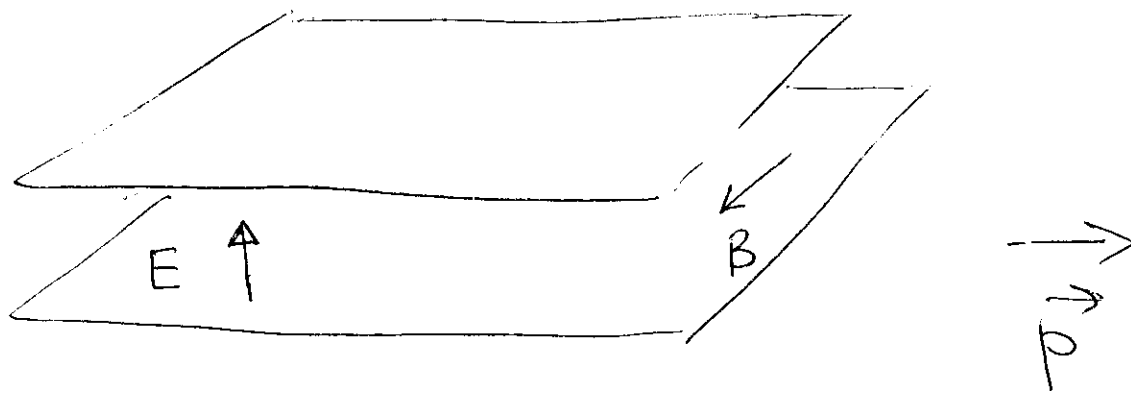


# Applications

1. Poynting vector
2. Stress tensor
3. Angular momentum



$$\vec{D} = \epsilon_0 \vec{E} \times \vec{B}$$

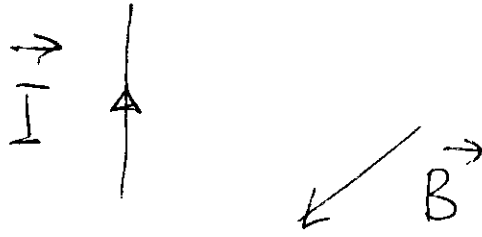
$$|\vec{E}| = \frac{1}{\epsilon_0} \frac{Q}{S}$$

$$\vec{D} = \int \vec{D} d^3r = \epsilon_0 \left( \vec{E} \times \vec{B} \right) \underbrace{V}_{Sd}$$

$$= \frac{Q}{\epsilon_0 S} \cdot Sd \left( \vec{n}_E \times \vec{B} \right)$$

$$= \frac{Qd}{\epsilon_0} \vec{n}_E \times \vec{B} =$$

$$= \underline{Qd \vec{n}_E \times \vec{B}}$$



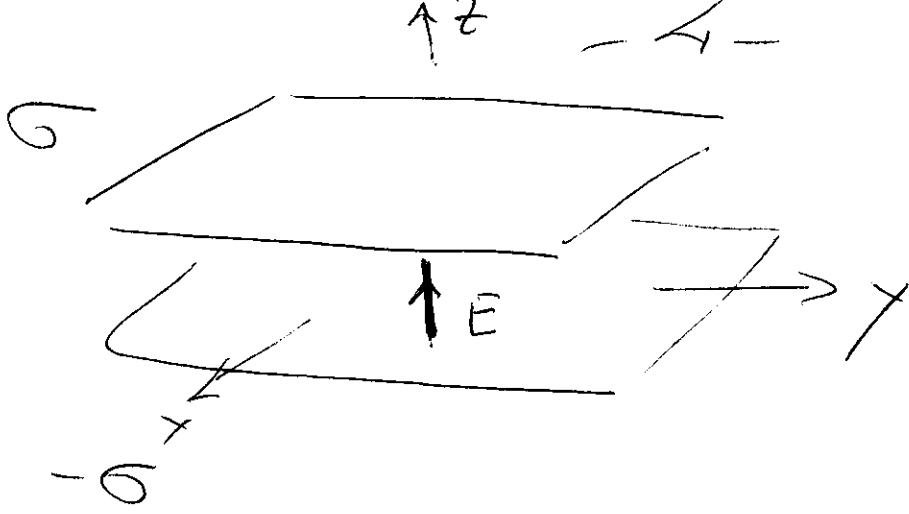
$$\vec{T} = \int \rho \vec{v} \times \vec{B} d^3r = \int \vec{J} \times \vec{B} d^3r$$

$$= \int \vec{I} \times \vec{B} dl =$$

$$= \vec{I} \times \vec{B} \cdot d$$

$$\vec{p} = \int \vec{F} dt = d \int \vec{I} dt \times \vec{B}$$

$$= \underline{Q d \vec{n}_I \times \vec{B}}$$



$$\vec{T} = \epsilon_0 \begin{pmatrix} -\frac{1}{2} \vec{E}^2 & & \\ & -\frac{1}{2} E^2 & \\ & & \frac{1}{2} \vec{E}^2 \end{pmatrix}$$

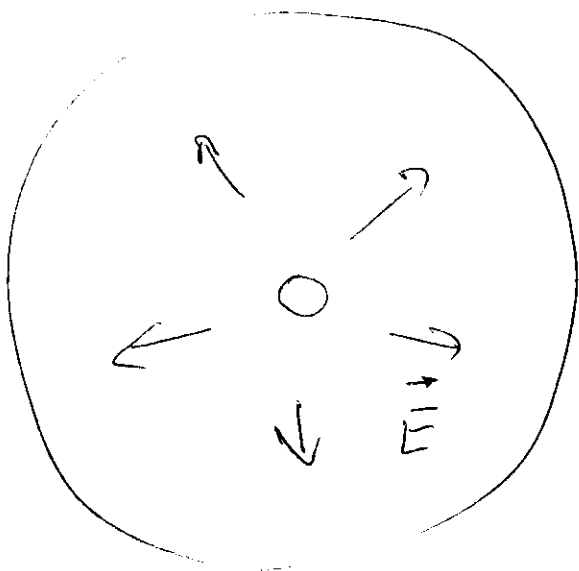
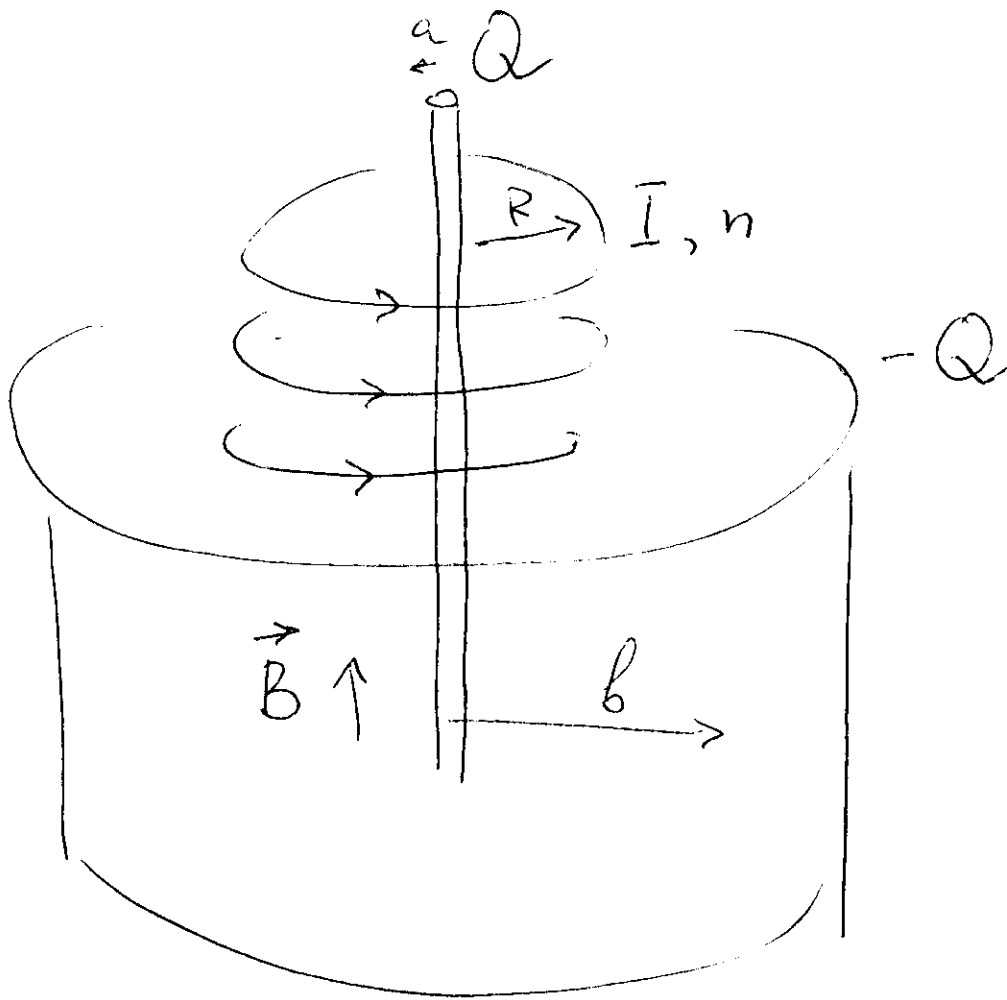
$$= \frac{\epsilon_0 \vec{E}^2}{2} \begin{pmatrix} -1 & & \\ & -1 & \\ & & 1 \end{pmatrix}$$

$$F_z = \left( \int \vec{T} \cdot d\vec{S} \right)_z = \frac{\epsilon_0 E^2 \cdot S}{2}$$

$$E = \frac{q}{\epsilon_0}$$

$$W = \frac{\epsilon_0 E^2}{2} \cdot S d$$

$$F = - \frac{\partial W}{\partial d} = - \frac{\epsilon_0 E^2 S}{2}$$



$$\vec{E} = \frac{Q}{2\pi\epsilon_0 l} \frac{\vec{n}_\rho}{\rho} \quad a < \rho < b$$

$$\vec{B} = \mu_0 n \vec{I} \vec{h}_z$$

$$\vec{\Phi}_{em} = \epsilon_0 \vec{E} \times \vec{B} = - \frac{\mu_0}{2\pi} \frac{n \vec{I} Q}{l \rho} \vec{h}_\varphi$$

$$\vec{L}_{em} \Rightarrow \int \vec{\rho} \times \vec{\Phi}_{em} = - \frac{\mu_0}{2\pi} \frac{n \vec{I} Q}{l} \vec{h}_z$$

$$\begin{aligned} \vec{L}_{em} &= - \frac{\mu_0}{2\pi} \frac{n \vec{I} Q}{l} \cdot \underbrace{V \cdot \vec{h}_z}_{\pi (R^2 - a^2) l} = \\ &= - \frac{\mu_0}{2} n \vec{I} Q (R^2 - a^2) \vec{h}_z \end{aligned}$$