PHYS 1A Work and EnergyJoe Wolfe, UNSWThe scalar product.dot productWhy? e.g. Work: scalar, related to \mathbf{F} , \mathbf{ds} and θ .



(also $dV = |\underline{\mathbf{E}}| |\underline{ds}| \cos \theta$ etc)



∴ define

 $\underline{\mathbf{a}} \cdot \underline{\mathbf{b}} \equiv \mathbf{ab} \cos \theta \quad (= \underline{\mathbf{b}} \cdot \underline{\mathbf{a}})$

Apply to unit vectors: $\mathbf{\underline{i}} \cdot \mathbf{\underline{i}} = 1 \cdot 1 \cos 0^\circ = 1 = \mathbf{\underline{j}} \cdot \mathbf{\underline{j}} = \mathbf{\underline{k}} \cdot \mathbf{\underline{k}}$ $\mathbf{\underline{i}} \cdot \mathbf{\underline{j}} = 1 \cdot 1 \cos 90^\circ = 0 = \mathbf{\underline{j}} \cdot \mathbf{\underline{k}} = \mathbf{\underline{k}} \cdot \mathbf{\underline{i}}$

Scalar product by components

$$\begin{split} \underline{\mathbf{a}} \, . \, \underline{\mathbf{b}} &= (a_x \, \underline{\mathbf{i}} + a_y \, \underline{\mathbf{j}} + a_z \, \underline{\mathbf{k}}).(b_x \, \underline{\mathbf{i}} + b_y \, \underline{\mathbf{j}} + b_z \, \underline{\mathbf{k}}) \\ &= (a_x b_x) \, \underline{\mathbf{i}} \, . \underline{\mathbf{i}} \, + (a_y b_y) \, \underline{\mathbf{j}}. \underline{\mathbf{j}} + (a_z b_z) \, \underline{\mathbf{k}}. \underline{\mathbf{k}} \\ &+ \, (a_x b_y + a_y b_x) \, \underline{\mathbf{i}}. \underline{\mathbf{j}} \, + \, (..) \, \underline{\mathbf{j}}. \underline{\mathbf{k}} \, + \, (..) \, \underline{\mathbf{k}}. \underline{\mathbf{i}} \end{split}$$

 $\underline{\mathbf{a}} \ . \ \underline{\mathbf{b}} \ = \ a_x b_x + a_y b_y + a_z b_z$

Problem. Find the angle between

 $\underline{\mathbf{a}} = 4 \, \underline{\mathbf{i}} - 3 \, \underline{\mathbf{j}} + 7 \, \underline{\mathbf{k}}$ $\underline{\mathbf{b}} = 2 \, \underline{\mathbf{i}} + 5 \, \underline{\mathbf{j}} - 3 \, \underline{\mathbf{k}}$ $ab \cos \theta = \underline{\mathbf{a}} \cdot \underline{\mathbf{b}} = a_x b_x + a_y b_y + a_z b_z$ $\cos \theta = \frac{a_x b_x + a_y b_y + a_z b_z}{\sqrt{a_x^2 + a_y^2 + a_z^2} \sqrt{b_x^2 + b_y^2 + b_z^2}}$ $\rightarrow \theta = 122^\circ$

Definition of work



When force varies, use differential displacement ds

$$dW = F ds \cos \theta$$

$$(F) (ds \cos \theta) \rightarrow F X \text{ component of } ds // F, \text{ or}$$

$$(F \cos \theta) (ds) \rightarrow ds X \text{ component of } F // ds$$

$$W = \int_{0}^{L} F \cos \theta ds$$

if F and θ *are constant*, we get W = FLcos θ SI Unit: 1 Newton x 1 metre = 1 Joule **Example**. How much work is done by lifting 100 kg vertically by 1.8 m very slowly?

Slow \therefore F_{applied} \cong mg W = mg d cos 0° = 1.8 kJ.

Not a lot, yet it is hard to do, because the force is inconveniently large. Consider:



If the rope and pulleys are light, and if the acclerations are negligible, then

Force on LH pulley

 $ma \cong 0 = 2T - mg$

 \therefore T = mg/2

If mass rises by D, word done = mgD. But rope shortens on both sides of rising pulley, if mass rises by D, rope must be pulled 2D, so work done = T * 2D = mgD



Example. What is the work done by gravity in a circular orbit?

 $W = \int F \, ds \, \cos \theta = 0$

Example. $F_{grav} \propto 1/r^2$. How much work is done to move m = 1 tonne from earth's surface (r = 6500 km) to r = ∞ ?

$$W = \int F \, ds \cos \theta$$

= $\int F \, dr$
$$F = -F_{grav} = \frac{Cm}{r^2}$$
 more later
On surface F/m = 9.8 ms⁻²

 $\therefore C = (9.8 \text{ ms}^{-2})(6.5 \text{ } 10^6 \text{ m})^2 = 4.1 \text{ } 10^{14} \text{ } \text{m}^3\text{s}^{-2}$

W =
$$\int_{6500}^{\infty} \frac{\text{Cm}}{\text{kmr}^2} dr$$

= $-\text{Cm}\left(\frac{1}{\infty} - \frac{1}{6.5\ 10^6}\right)$
= $6.3\ 10^{10} \text{ J}$ = $63 \text{ GJ}.$

Work to deform spring



No applied force (x = 0)Hooke's law: F = -kxWork done **by** spring $= \int F_{spring.} dx$ $= \int -kx. dx = -\frac{1}{2} kx^2$ Work done **on** spring $= \int F_{applied.} dx$ $= \int kx. dx = +\frac{1}{2} kx^2$ (= work stored in spring)

The work-energy theorem

(Total) force F acts on mass m in x direction.

 $F = \frac{v_{i}}{F}$ Work done by $F = \int_{i}^{f} F dx$ (use F = ma) $= \int_{i}^{f} m \frac{dv}{dt} dx = \int_{i}^{f} m \frac{dx}{dt} dv$ $= \int_{i}^{f} mv.dv = \left[\frac{1}{2}mv^{2}\right]_{i}^{f}$ Work done by $F = \frac{1}{2}mv_{f}^{2} - \frac{1}{2}mv_{i}^{2} \equiv \Delta K$

Define **kinetic energy** $K \equiv \frac{1}{2}mv^2$

Increase in kinetic energy of body = work done by **total** force acting on it.

This is a theorem, ie a tautology because it is only true by definition of KE and by Newton 2. ∴ restatement of Newton 2 in terms of energy. Not a new law

is the rate of doing work Power.

 $\bar{\mathbf{P}} \equiv \frac{\mathbf{W}}{\Delta t}$ Average power $\mathbf{P} = \frac{\mathbf{dW}}{\mathbf{dt}}$ Instantaneous power

SI unit: 1 Joule per second \equiv 1 Watt (1 W) **Example** Jill (m = 60 kg) climbs the stairs in Matthews Bldg and rises 50 m in 1 minute. How much work does she do against gravity? What is her average output power? (neglect accelerations)

$$W = \int \mathbf{F} \cdot \mathbf{ds} = \int F_y \, dy$$

$$F_y \cong mg$$

$$W = mg \int dy = mg \Delta y$$

$$= 29 \text{ kJ} \qquad (cf K = \frac{1}{2}mv^2 \sim 20 - 40 \text{ J})$$

 $\equiv \frac{W}{\Delta t} = \frac{mg \,\Delta y}{\Delta t} = 490 W$ Ē

(humans can produce 100s of W, car engines several tens of kW)

 $(1 \text{ horsepower} \equiv 550 \text{ ft.lb.s}^{-1} = 0.76 \text{ kW})$

Potential energy.

e.g. Compress spring, do W on it, but get no K. Yet can get energy out: spring can expand and give K to a mass. \rightarrow Idea of stored energy.

e.g. Gravity: lift object (slowly), do work but get no K. Yet object can fall back down and get K. Recall $W_{against grav} = mg \Delta y$ i.e. W = W(y)

But: Slide mass slowly along a surface. Do work against friction, but can't recover this energy mechanically. Not all forces "store" energy

Conservative and non-conservative forces

(same examples)

$$W_{\text{against grav}} = -\int_{i}^{f} F_{g} dr \cos \theta$$
$$= -\int_{i}^{f} F_{g} dz$$
$$= mg \int_{i}^{f} dz$$
$$= mg (z_{f} - z_{i}) \qquad in \text{ uniform field}$$

W is uniquely defined at all \mathbf{r} , i.e. W = W(\mathbf{r}) If $z_f - z_i$ are the same, W = 0.

Work done against gravity round a closed path = 0*.*.. Gravity is a **conservative force**

Compare spring



with friction

 $dW_{against fric} = -F_f ds \cos \theta$

but $\underline{\mathbf{F}}_{f}$ always has a component *opposite* $\underline{\mathbf{ds}}$

 \therefore dW always ≥ 0 . (we never get work back)

:. cannot be zero round closed path, :. $W \neq W(\underline{\bm{r}})$

\therefore friction is a **non-conservative force**

Note that direction of friction (dissipative force) is always against motion.

Potential energy

For a **conservative** force $\underline{\mathbf{F}}$ (i.e. one where work done against it, $W = W(\underline{\mathbf{r}})$) we can define potential energy U by $\Delta U = W_{against}$. i.e.

$$\Delta U = -\int_{i}^{f} F \, dr \cos \theta$$

Same example: spring

$$\Delta U_{spring} = -\int_{i}^{f} F_{spring} dx$$
$$= -\frac{1}{2} k(x_{f}^{2} - x_{i}^{2})$$

Choice of zero for U is arbitrary. Here U = 0 at x = 0 is obvious, so

$$U_{spring} = \frac{1}{2} kx^2$$

From energy to force:

 $U = -\int F \, ds$ where ds is in the direction // F

$$F = -\frac{dU}{ds}$$

in fact $F_x = -\frac{dU}{dx}, F_y = -\frac{dU}{dy}, F_z = -\frac{dU}{dz}$

Spring: $U_{spring} = \frac{1}{2}kx^2$ \therefore $F_{spring} = -kx$ Gravity: $U_g = mgz$ \therefore $F_g = -\frac{dU}{dz} = -mg$ Energy of interaction:



Conservation of mechanical energy

Recall: Increase in K of body = work done by **total** force acting on it. (restatement of Newton 2) But, if all forces are conservative, work done by these forces = $-\Delta U$ $(definition \ of \ U)$ \therefore if only conservative forces act, $\Delta K = -\Delta U$ We define mechanical energy $E \equiv K + U$ so, if only conservative forces act, $\Delta E = 0$. we can make this stronger. Work done by non-conservative forces Define internal energy Uint where $\Delta U_{int} = -$ Work done by n-c forces (= + Work done **against** n-c forces) Recall defⁿ of K: ΔK = work done by Σ force $\Delta K = -\Delta U - \Delta U_{int}$... $\Delta K + \Delta U + \Delta U_{int} = 0$ ÷. If n-c forces do no work, then $\Delta U_{int} = 0$, so: If non-conservative forces do no work, $\Delta E \equiv \Delta K + \Delta U = 0$ mechanical energy E is conserved or: Equivalent to Newton 2, but useful for many mechanics problems where integration is difficult. State the principle carefully! Never, ever write: "kinetic energy = potential energy" **Classic problem.** Child pushes off with v_i. How fast is the s/he going at the bottom of the slide? Neglect friction (*a non-conservative force*).



i) By Newton 2 directly: $v = \int_{top}^{bottom} dt = \int_{top}^{bottom} \frac{F}{m} = \int_{top}^{bottom} g \cos \theta dt =$

Using work energy theorem (Newton 2 indirectly):
 Non-conservative forces do no work, ∴ mechanical energy is conserved, i.e.

$$\begin{split} \Delta E &= \Delta K + \Delta U = 0 & E_f = E_i \\ K_f - K_i + U_f - U_i = 0 & or & K_f + U_f = K_i + U_i \\ &\frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2 + mgy_f - mgy_i = 0 \end{split}$$

rearrange $\rightarrow v_f = \sqrt{v_i^2 + 2g(y_i - y_f)}$

Conservation of energy

observation: for many forces, $W = W(\underline{\mathbf{r}})$: useful to define $U = U(\underline{\mathbf{r}})$. *observation:* for all systems yet studied, U_{int} is a state function, i.e. $U_{int} = U_{int}$ (measured variables) Hence idea of internal energy. e.g.: *Friction,* $(-U_{int}) =$ heat produced when work is done against friction. *Air resistance* $(-U_{int})$ is sound and heat. *Combustion engines and animals:* $+U_{int}$ comes from chemical energy

$$\Delta \mathbf{K} + \Delta \mathbf{U} + \Delta \mathbf{U}_{\text{int}} = \mathbf{0}$$

is statement of Newton 2 plus definitions of K, U, U_{int} . The statement that ΔU_{int} is a state function is the first law of

thermodynamics. It is a law, ie falsifiable. More on this in Heat.

Example. Freda (m = 60 kg) rides pogo stick (m \ll 60 kg) with spring constant k = 100 kN.m⁻¹. Neglecting friction, how far does spring compress if jumps are 50 cm high?



Non-conservative forces do no work, \therefore mechanical energy is conserved, i.e.

$$\begin{split} E_{bottom} &= E_{top} \\ K_b + U_b &= K_t + U_t \qquad (U = U_{grav} + U_{spring}) \\ \frac{1}{2} mv_{horiz}^2 + (mgy_b + \frac{1}{2} kx_b^2) \\ &\cong \frac{1}{2} mv_{horiz}^2 + (mgy_t + \frac{1}{2} kx_t^2) \\ mg(y_t - y_b) &\cong \frac{1}{2} kx_b^2 \\ \therefore \quad x_b &\cong \sqrt{\frac{2mg(y_t - y_b)}{k}} \cong 80 \text{ mm.} \end{split}$$



Example. Slide starts at height h_1 . Later there is a hump with height h_2 and (vertical) radius r. What is the minimum value of $h_2 - h_1$ if slider is to become airborne? Neglect friction, air resistance.

Over hump, $a_c = \frac{v^2}{r}$ (down). Airborne if $g < a_c$, i.e. if $v_2^2 > gr$.

No non-conservative forces act so

$$E_{2} = E_{1}$$

$$U_{2} + K_{2} = U_{1} + K_{1}$$

$$mgy_{2} + \frac{1}{2}mv_{2}^{2} = mgy_{1} + \frac{1}{2}mv_{1}^{2}$$

$$\frac{1}{2}mv_{2}^{2} = mg(y_{1} - y_{2})$$

$$(y_{1} - y_{2}) = \frac{v_{2}^{2}}{2g} > \frac{gr}{2g} = \frac{r}{2}$$

Example Bicycle and rider (80 kg) travelling at 20 m.s⁻¹ stop without skidding. $\mu_s = 1.1$. What is minimum stopping distance? How much work done by friction between tire and road? Between brake pad and rim? Wheel rim is ~300 g with specific heat ~ 1 kj.kg⁻¹, how hot does it get?

friction \rightarrow *declleration* \rightarrow *stopping distance*

$$\begin{aligned} |\mathbf{a}| &= \frac{\mathbf{F}_{f}}{\mathbf{m}} \leq \frac{\mu_{s} \mathbf{N}}{\mathbf{m}} = \mu_{s} \mathbf{g} \\ |\mathbf{a}| &\leq \mu_{s} \mathbf{g} \\ \mathbf{v}_{f}^{2} - \mathbf{v}_{i}^{2} = 2\mathbf{a} \mathbf{s} \quad \rightarrow \quad \mathbf{s} = \frac{\mathbf{v}_{f}^{2} - \mathbf{v}_{i}^{2}}{2\mathbf{a}} \\ \mathbf{s} \geq \left| \frac{-\mathbf{v}_{i}^{2}}{2\mu_{s} \mathbf{g}} \right| = 19 \text{ m} \end{aligned}$$

Work done by friction between tire and road? No skidding, \therefore no relative motion, \therefore W = 0. Between pad and rim? Here \exists relative motion. All K of bike & rider \rightarrow heat in rim and pad

$$\begin{array}{rcl} W &=& \Delta K &=& K_f - K_i &=& - \ 16 \ kJ \\ Q &=& m C \Delta T & \ldots \dots & \Delta T \ \sim \ 50 \ ^\circ C \end{array}$$

Example Which way is it easier to drag an object?



Suppose we move at steady speed, a = 0. Which requires less F? Which requires less work?

Work done = Fs cos θ = F_fs = $\mu_k Ns = \mu_k s(mg - F \sin \theta)$ decreases with θ

Question



How high should h be so that it can loop the loop?

Example. A hydroelectric dam is 100 m tall. Assuming that the turbines and generators are 100% efficient, and neglecting friction, calculate the flow of water required to produce 10 MW of power. The output pipes have a cross section of 5 m².



Nett effect: ~ stationary water lost from *top* of dam, water appears with speed v at bottom.

Let flow be $\frac{dm}{dt}$. $dW \equiv \frac{work \ done}{by \ water} = -\frac{work \ done}{of \ water} = -\frac{energy \ increase}{of \ water}$ dW = -dE = -dK - dU $= -\left(\frac{1}{2} \ dmv^2 - 0\right) - \left(0 - dm.gh\right) = \ dm\left(gh - \frac{v^2}{2}\right)$ $P = \frac{dW}{dt} = \frac{dm}{dt}\left(gh - \frac{v^2}{2}\right)$ Problem: v depends on $\frac{dm}{dt}$ $\underbrace{\bigvee}_{v.dt} \qquad \underbrace{\bigvee}_{v.dt} \qquad \underbrace{\frac{dV}{dt} = \frac{A.(v.dt)}{dt} = Av}_{v.dt} = \frac{mass}{volume} = \frac{m}{V} \quad \text{so } m = \rho V$ $\frac{dm}{dt} = \rho \frac{dV}{dt} = \rho Av$ $P = \rho Av\left(gh - \frac{v^2}{2}\right)$ $v^3 - (2gh)v + \frac{2P}{\rho A} = 0 \quad can \ solve \ cubit, \ but \ messy}$ Neglect $v^3 \rightarrow v = \frac{P}{gh\rho A} = 2 \text{ m/s}$ and indeed we see that $v^3 < other \ terms$